

1 **Mechanical mechanisms of morphogenesis as potential**
2 **substrates for evolutionary change**

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18 **Abstract**

19 The first quarter of this century has seen a resurgence of interest in the mechanical and physical
20 mechanisms that drive cellular behaviors in the context of morphogenesis. Far from being a new
21 discovery, the fact that the material properties of cells and the physical forces that they exert ad
22 experience must play decisive roles in development, was an important part of the field of
23 experimental embryology well over a century ago. Following the birth of molecular biology, and
24 the development of live imaging approaches that can capture the dynamics of both cellular
25 properties and materials, and the activity of genes and gene products, the current manifestation
26 of this field promises to link mechanical and molecular genetic mechanisms. Here we review
27 recent advances in understanding the relationships between mechanical and molecular genetic
28 mechanisms, and suggest paths forward that could yield answers to the pressing questions of
29 whether and evolutionary forces act not only on functional morphologies, but also on the
30 mechanical forces that create them.

31 **Keywords**

32

33 Physics; forces; cytoskeleton; genetics; materials; development

34

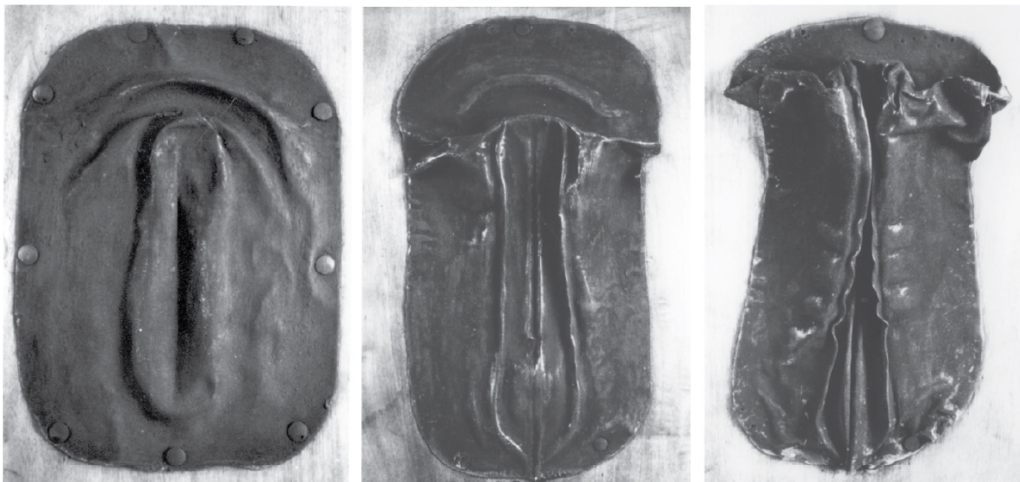
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36 **Introduction**

37

38 Much like a bust is carved through sequences of tool-born forces against marble or a
39 house built from the fastening of wooden posts, multicellular organisms are constructed through
40 specific actions of removing, adding, connecting, and refiguring the materials that constitute them.
41 The result of these transformations during development, what we consider here as
42 morphogenesis, is the generation of forms – segments, organs, limbs, connective tissues, etc. –
43 that organize the body and give organisms the ability to reproduce, move, communicate, and
44 absorb nutrients, among other essential physiological tasks. The diversity of ways that extant
45 multicellular species engage their environments reflects the long evolutionary history of these
46 form-generating processes.

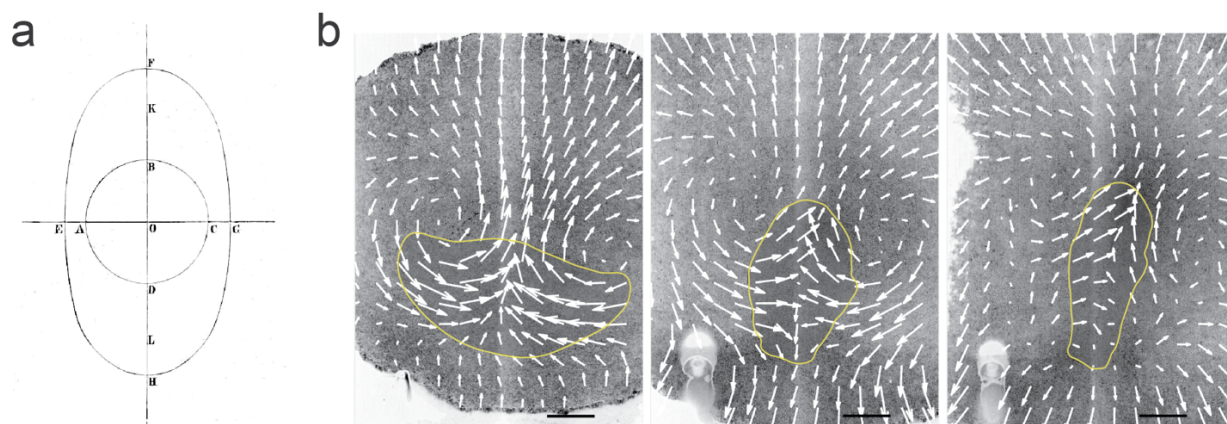
47 It has been appreciated for over a century that physical forces and material properties of
48 cells and tissues—akin to those of marble or wood—play a central role in multicellular development.
49 In the 1860s, only a few years after the publication of Darwin’s *On the Origin of Species* [1], the
50 embryologist Wilhelm His constructed “mechanical” models of early-stage chick embryos in which
51 he deformed lead plates to approximate their emerging form [2] (**Figure 1**).



52

53 **Figure 1.** Wilhelm His' developmental series of the early chick embryo in which development is modeled
54 as the physical deformation of a pliable lead plate (circa 1866-67). Reprinted with permission from the
55 Anatomisches Museum Basel.
56

57 His also collaborated with the mathematician Eduard Hagenbach to mathematically model
58 the chick embryo as a sheet with zones of differential elasticity [3] (**Figure 2**). His was a proponent
59 of the cytoplasm as the locus of morphogenetic “anlagen,” [4] meaning that he considered that
60 the rudimentary or foundational contributors to morphogenesis, were to be found in the cytoplasm
61 of cells. His’ approach would influence Wilhelm Roux’s program of developmental mechanics [5,6]
62 as well as D’Arcy Thompson’s *On Growth and Form* decades later [7,8]. Even though embryology
63 played a central role in nineteenth century conceptions of species transformation [9], questions
64 of ontogeny would become increasingly siloed from those of phylogeny in subsequent decades
65 [10].
66



67
68 **Figure 2.** Mathematical and physical descriptions of early chick development. At these stages, the chick
69 embryo is a relatively flat, round disk. **a** Schematic of the chick embryo from “Change in Form of a Thin,
70 Incompletely Elastic Plate, of Which Different Parts Grow Unequally” by Eduard Hagenbach (title translation
71 from [2], published in Wilhelm His’ *Untersuchungen über die erste Anlage des Wirbelthierleibes: die erste*
72 *Entwicklung des Hühnchens im Ei* [3]) **b** Three chronologically consecutive stages (Hamburger Hamilton
73 stages [11]HH1, HH2 and HH3 from left to right) of a gastrulating chick embryo. The regions outlined in
74 yellow undergo convergent extension and ingression to generate the tissue flows indicated by the white
75 arrows (velocity). Scale bars = 500 μ m. Modified from Figure 1 in [12].
76

77 By the end of the twentieth century, the physical and material processes of form-
78 generation as a causal force in development and morphogenesis had become sidelined. The rise
79 of genetics and molecular biology infused mainstream evolutionary and developmental biology,
80 which became nearly synonymous with developmental genetics, with explanatory frameworks
81 that reduced development and evolution to the action of individual or networks of genes [13–15].
82 The mechanics of form-building was by-and-large understood to be explained entirely by genetic
83 “programming” and natural selection on genetic variation [16–18].

84 Given this history, the first decades of twentieth century evolutionary developmental
85 biology, or “evo-devo,” leveraged the gene as the pivot point between scales and broader
86 evolutionary relationships. Indeed, some of the most highly cited papers on the topic of the
87 evolution of morphogenesis—specifically of animal eyes and vertebrate limbs—build their
88 explanations around the presence of the same individual “master” genes or gene families across
89 species [19–21].¹ This molecular orientation, which has continued to permeate contemporary
90 research, has also skewed the narrative of evo-devo’s history towards the identification and
91 cloning of conserved body patterning genes across diverse phyla [22].

92 From its inception, however, evo-devo included morphogenetic perspectives. The physical
93 aspect of form-generation was a central interest of John Tyler Bonner, who studied
94 morphogenesis in cellular slime molds and organized the catalyzing 1981 Dahlem Workshop on
95 Evolution and Development [23–25]. Bonner was heavily influenced by D’Arcy Thompson and
96 embryologists of the mid-twentieth century who embraced explanations of development that
97 accounted for dynamic, form-generating processes emerging at the level of cells and tissues
98 [15,26]. Placing morphogenesis more squarely in an evolutionary context, Pere Alberch—who
99 participated in the 1981 workshop along with like-minded colleagues such as Stephen J. Gould—

¹ We determined this using the citation metric from a Web of Science database we created by searching for “evolution” and “morphogenesis” in the Zoological Record, CABI, and Biosis Index databases. These databases are curated by experts trained in the various disciplines and topics each covers. The papers cited here were in the top five most cited papers among our search results.

100 advocated for the dynamic interactions of cells and the morphogenetic rules that emerge from
101 them as the prime constraints driving evolutionary transformation [27,28].

102 Within the past fifteen years, there has been a resurgence of interest in the physics of
103 development [29]. This growing literature has made clear that while the transcription of a gene or
104 the subcellular localization of its protein products can set the parameters for or “trigger” physical
105 transformations of tissue, many such transformations can be accounted for irrespective of these
106 triggering events [16]. There has also been a more recent recognition within contemporary biology
107 of the limitations of genetic reductionism in explanations of biological phenomena [28,30,31]. The
108 fact that this has had to be re-stated in the current decade highlights the persistent perception of
109 genetic explanations as universal, and the mechanistic rigor that continues to be attributed to
110 them [13]. However, this emerging literature has been largely limited to explaining processes at
111 particular temporal and spatial scales of biological organization, and currently leaves many open
112 questions as to how the generation of form is subject to evolutionary change.

113 How do mechanical constraints drive not only the emergence of form in individuals but
114 also the evolution of morphologies? Mechanics and geometries, which arise from the physio-
115 chemical properties of cell-material (adhesion, cytoskeletal tensions, cytoplasmic viscosity, etc.),
116 are elements of development that may be subject to natural selection just as much as variants of
117 gene sequences. The dynamics of these properties, as the evolutionary biologist Keith Thomson
118 has put it, “add their own layer of causal influence in evolution” [17]. Our position is not that genes
119 are dispensable for the evolution of morphogenesis. As we discuss, they produce proteins that
120 generate, catalyze, and regulate the material used to build biological structures at every length
121 scale. Naturally, constraints emerge from the properties of available materials—properties that are
122 indeed contributed to by DNA sequence and regulatory variations—and their respective
123 interactions, generating an allowed space of morphological variations [32]. Many genes—the suite
124 of *Drosophila melanogaster* segmentation genes, for example—also provide essential cues or set
125 transcriptional profiles in motion. But the cellular or sub-cellular mechanistic processes caused

126 by such genes must be integrated with mechanical, or physical, causes of morphogenesis across
127 scales at high temporal resolution.² We propose that environment-specific parameters together
128 with corresponding fitness contributions of a structure determine whether a morphology is
129 stabilized or diversified across evolutionary time.

130 Here, we review recent literature, primarily drawn from studies of Metazoa, that point
131 towards two promising avenues for broadening the field's perspective beyond genetic
132 reductionism and further integrating temporal and spatial scales in studies of morphogenesis and
133 evolution. Our first focus is literature that is beginning to couple gene expression with the physics
134 of the cell and tissue, or organismic, scale. This literature suggests that the mechanics of cells
135 and tissues can regulate transcription, suggesting not only a direct relationship between forces
136 that organisms experience at the cell or tissue scale with regulation at the genetic, molecular
137 scale, but also that the causal connection between the two is bidirectional. This area of
138 investigation requires us to be specific in the language we use to describe the exact role genes
139 play in our explanations of morphogenesis.³

140 We then turn to phenomena that are difficult to detect with the traditional approaches of
141 evolutionary or developmental genetics. The production of cell shape, cytoskeletal meshes, and
142 differential adhesion, for example, all require genes to produce the raw materials they are
143 constructed from. But we cannot understand how these materials come together to produce
144 functional architectures simply by detecting the presence of gene products. Nor is it sufficient to
145 limit our assessment of causation to the elimination or substitution of nucleic acid or amino acid
146 sequences.⁴ Rather, we need to spatially describe the emergence of form at high temporal

² Palmquist et al. have outlined two kinds of reductionism commonly used in contemporary developmental biology: temporal and length-scale reductionism. Recognizing the limits of these two kinds of reductionism is key for expanding our explanatory frameworks [31].

³ The ambiguity of the "gene" has existed since the term was first introduced in the early 1900s [174]. Decades later T.H. Morgan wrote that there was still "no consensus opinion among geneticists as to what the genes are" [13]. Today, we know an immense amount about the architecture and activities of genes, yet these distinctions are still often glossed over in the catch-all notion of the "gene."

⁴ Laura Nuño de la Rosa and Gerd Müller have articulated nicely how biological causality has been traditionally attributed in developmental genetics: "Developmental genetics typically perceives development as a sequence of gene

147 resolution. As we discuss, a wide range of morphologies across phyla can be produced from
148 highly conserved genes and their products—actin, non-muscle myosin, tubulin, cadherins, etc..
149 What matters for the phenotype is how, where, and when these products are assembled in
150 specific physical and mechanical contexts. Further, form at one time point in development can
151 itself have a regulative role in determining the emergence of form at the next time point. In sum,
152 forms that emerge from dynamics at the molecular scale can themselves regulate development
153 without the need for information from genes.

154 Together, these foci suggest two approaches to identifying substrates other than gene
155 sequences, and the molecular products that they encode, for potential evolutionary change.
156 Whereas the first involves making causal connections between genes, molecules and the
157 mechanics of cellular collectives, the second shifts attention to the tissue and organ levels of
158 biological organization, where the mechanics of multicellular form-building emerge. In the second
159 approach, seeking an exclusively genetic “cause” is likely to be fruitless, as these phenomena
160 cannot be explained at the genetic scale alone.

161

162 **1. Mechanical control of gene expression**

163
164 In this section, we argue that morphologies are not simply the end products of genetic
165 information but instead play an instructive or permissive role in gene expression, potentially
166 influencing evolution. To support this idea, we draw attention to recent studies that link the
167 mechanical states of cells and tissues to changes in gene expression. Specifically, we highlight
168 evidence showing that mechanical forces are crucial in metazoan development, activating the first

expressions revealed through an interventionist methodology wherein induced genetic alterations yield discrete phenotypic changes. This procedure traces a chain of events from perturbation to consequence, attributing causal significance to the altered gene in the developmental process. From an organismic perspective, this approach has significant limitations: while it identifies certain causal elements, it fails to elucidate the complex suite of interactions that determine the final phenotypic outcomes.” [p.3 in 28].

169 zygotic genes that determine germ layers and early cell types. For clarity, we do not include an
170 extensive discussion focused on many different types of dedicated mechanosensory proteins, as
171 these issues have been well covered by other authors [33–38]. The role of mechanosensory
172 molecules has also been discussed in detail elsewhere [39–42]. Instead, we emphasize how the
173 morphological state of tissues actively drives expression patterns of a wide range of genes,
174 illustrating a widespread reciprocal relationship between form and function.

175

176 1.1 Tissue scale morphogenesis

177 Over the past few decades, it has become clear that cells constantly sense and respond
178 to their mechanical environment in predictable ways [43]. For example, outside the context of
179 embryology, the role of substrate stiffness in guiding neuronal growth, neural crest migration, and
180 stem cell fate has been well established [44–46]. Developing neurons and glial cells are highly
181 sensitive to the stiffness of the extracellular matrix, using this mechanical information to regulate
182 processes including proliferation, differentiation and axonal growth [47,48]. These functions are
183 essential for shaping proper morphogenetic outcomes, including the formation of the brain, spinal
184 cord, and motor neurons. Studies of these phenomena, conducted primarily in isolated cells, have
185 largely examined how intracellular signaling pathways respond to artificially induced mechanical
186 stress or substrate stiffness. While these investigations have provided valuable insights into
187 cellular signaling, they do not address how cells respond to the mechanical forces that arise
188 naturally during tissue morphogenesis. These forces, unlike external manipulations, emerge as a
189 direct consequence of cell behaviors themselves. Moreover, the dynamic interplay between
190 mechanically altered cell behavior and the evolving geometry of the tissue, both in time and space,
191 remains poorly understood.

192 Across animals, mechanical forces play a pivotal role during embryogenesis, shaping the
193 entire embryo through a combination of local cellular movements and specialized structures

194 spanning multiple cells [49–55]. Key stages of early development, such as gastrulation, are
195 marked by dramatic, large-scale morphogenetic movements. Collective motion of cells generates
196 forces which act at a tissue scale, determining the future identities of different embryonic regions.
197 Much like the deformations crafted in Wilhelm His' lead-sheet models (**Figure 1**), asymmetrical
198 tension within an embryo-wide contractile actomyosin ring drives the formation of the primitive
199 streak in gastrulating quail embryos [56]. This asymmetry in tissue contractility not only shapes
200 embryonic structure but also regulates the expression of early fate-determining genes across
201 distinct regions of the embryo. Perturbing this asymmetric contractility leads to the formation of
202 additional ectopic embryos, underscoring the critical role of geometric force patterns, rather than
203 just the presence or absence of mechanical forces, in guiding gene expression [57].

204 The evolutionary diversification of embryogenesis may be linked to how mechanical forces
205 interface with gene expression. In chick embryos, alterations in cell-autonomous behaviors and
206 supracellular actomyosin cables modified stereotypical tissue morphologies, producing
207 gastrulation patterns resembling those of evolutionarily distinct vertebrate groups, such as
208 amphibians, reptiles, and fishes [58]. Echoing Hagenbach's earlier efforts (**Figure 2**), Serra and
209 colleagues [12] proposed a minimal mechanochemical model that, by varying only initial
210 conditions and a single cellular behavior, accurately predicted tissue flows during gastrulation
211 across these vertebrate groups. It is striking that such morphological diversity can arise from a
212 limited set of signaling nodes that couple tissue mechanics to cellular behavior. Connecting such
213 changes in tissue mechanics, and thereby gastrulation modes [see 59], with species-specific
214 spatial patterns of downstream gene expression is a promising avenue for further investigation.

215 One of the most studied molecular nodes in force-dependent germ layer specification is
216 β -catenin, known for its dual role as a junctional protein and a transcription factor [reviewed in
217 60]. Across metazoans, β -catenin mediates mechanical regulation of gene expression to specify
218 germ layer identity [61–66]. This general role appears to be both ancient and conserved across
219 animals, with functional evidence for this hypothesis emerging from studies in cnidarians [67] and

220 ctenophores [68]. However, the specific ways that β -catenin is linked to tissue mechanics, and
221 the downstream signaling pathways thus triggered, show some evolutionary divergence.

222 In the clawed frog *Xenopus laevis*, embryonic β -catenin activity patterns are critical for
223 dorsal-ventral axis patterning [69–71], tissue movements associated with the formation of the
224 blastopore [72], and early mesodermal identity [73]. In embryos of the quail *Coturnix japonica*, β -
225 catenin activity shares functional similarity to that in amphibians, in that it partially determines
226 early mesodermal identity [57]. In contrast to *X. laevis*, however, inhibiting β -catenin activity in the
227 quail embryo does not disrupt tissue flows leading to the formation of the primitive streak [57].
228 This divergence of β -catenin activity in regulating the formation of equivalent structures in
229 amphibians and avian embryos suggests that while β -catenin retains a central role in force-
230 mediated gene-expression in vertebrates, its functional outcomes may have changed across
231 evolutionary lineages.

232 Another example of divergence in β -catenin activity is found in invertebrate
233 deuterostomes, notably echinoderms and ascidians. In echinoderms, β -catenin activity regulates
234 endoderm and mesoderm specification in a dose-dependent manner along the primary embryonic
235 axis, with its peak activity restricted to the vegetal pole [63,74]. Studies on sea urchin embryos
236 (echinoderms) show that endomesoderm specification is governed by the fine spatiotemporal
237 control of β -catenin activity and degradation along the animal-vegetal axis [75,76]. In sea squirts
238 (ascidians), β -catenin activity-mediated endomesoderm specification occurs at the 8-cell stage,
239 significantly earlier than in echinoderms [62]. In contrast to the gradient of β -catenin activity
240 observed in echinoderms, in studied ascidians a binary on-off switch between the 16 and 32 cell
241 stages determines endodermal and ectodermal fates [62]. To our knowledge, these examples
242 lack a mechanical explanation for the observed divergence in β -catenin activity. Investigating how
243 force-dependent β -catenin activity emerges in these animals using an experimental and
244 theoretical framework similar to that of the previously highlighted studies [12,56–58,77,78][77,78],

245 including *in vitro* experiments comparing beta-catenin activity and function, could provide valuable
246 insights into the evolutionary mechanisms shaping morphogenesis.

247

248 1.2 Force transmission in the nucleus

249 The force-induced nuclear translocation of molecules is often regarded as an indicator of
250 their involvement in gene expression. β -catenin, when mechanically activated, translocates to the
251 nucleus to drive the expression of both the canonical Wnt pathway and of non-canonical target
252 genes [60,79]. In this framework, the genome is viewed as a static repository, where genes
253 become available for transcription upon the right stoichiometric assembly of transcription factors,
254 co-factors, and complexes. However, recent evidence suggests that the spatial organization of
255 the genome itself plays a crucial role in regulating gene expression, adding another layer of
256 complexity to this process.

257 Eukaryotic genomes are organized into complex three-dimensional architectures
258 spanning multiple length scales. This organization ranges from smaller structural elements, such
259 as DNA loops and domains, to larger structures like entire chromosomes [reviewed in 80]. The
260 condensation state, or spatial configuration, of chromatin determines the accessibility of genes to
261 transcription factors, thereby regulating gene expression [81]. Gene expression patterns
262 concomitant with changing structural organization of the genome are therefore more appropriately
263 considered as probability functions rather than binary on/off switches [82,83]. In this section, we
264 discuss how forces experienced at the cell and subcellular scale—including those generated by
265 the physics of genetic material itself— can regulate gene expression.

266 During tissue morphogenesis, cells take up diverse morphologies resulting from a variety
267 of stress and strain generated by surrounding tissues. These mechanical states can be transitory
268 [84] or long-lasting [85,86]. We speculate that altered genome structure during such periods might
269 drive specific gene expression patterns or even enable differentiation of cell types. Wei and

270 colleagues showed that the angle of applied stress on Chinese Hamster Ovary cells determined
271 the degree of chromatin stretching [87]. This impact of the stress angle was mediated by the initial
272 orientation of pre-existing actin stress fibers in the cells. In addition, the stress angle and duration
273 directly controlled expression levels of a target gene.

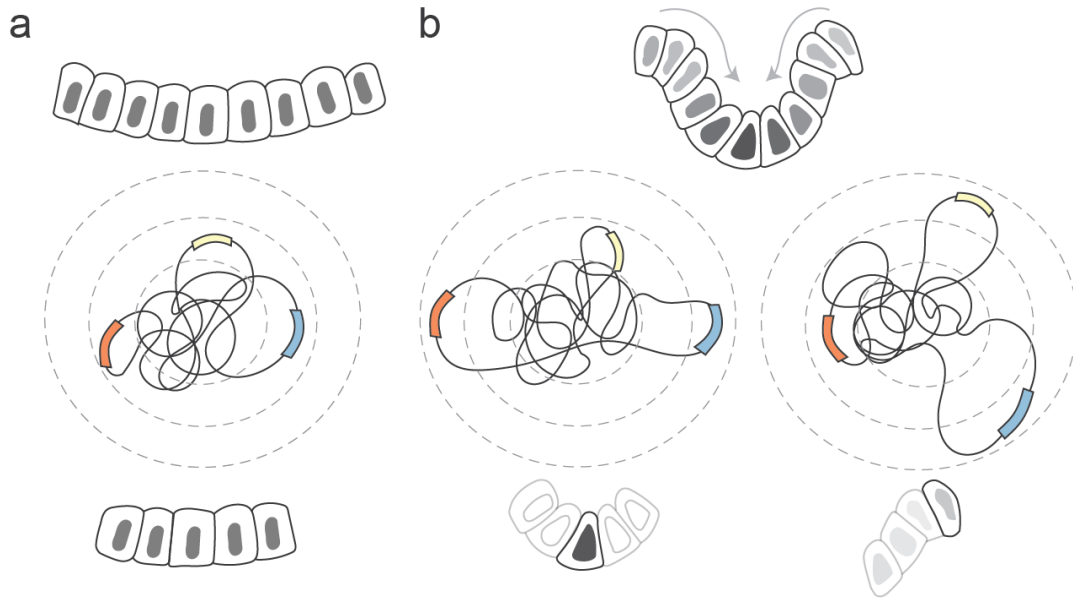
274 Looking at mechanics at the subcellular scale, Matsushita and colleagues showed that
275 human mesenchymal cells undergoing differentiation into osteoblasts exhibit gradual changes in
276 nuclear viscoelastic properties [88]. These changes are driven by alterations in chromatin
277 condensation and DNA packing, which collectively shape the chromatin meshwork—a key
278 determinant of nuclear viscoelasticity. A growing body of evidence [89–92] suggests that the
279 physical nature of the nuclear genome is “fluid-like”, and thus constantly coupled to the
280 mechanical state of the cell. Keizer and colleagues [91] directly measured the physical dynamics
281 of a single genomic locus by applying magnetic point forces. Combining single-molecule imaging
282 with different regimes of pulling and recoil, they found that weak (near-piconewton) forces could
283 generate relatively large-scale movements of a genomic locus. It is likely that extracellular stress
284 and strain, even when partially transmitted to the nucleus, may influence gene expression by
285 repositioning a genomic region to make it more accessible to transcription factors.

286 While chromatin rearrangement may explain temporary transcriptomic responses to force,
287 stable gene expression and cellular differentiation are likely to require more permanent
288 alterations. Tissue morphogenesis is a highly dynamic process where forces experienced by a
289 cell constantly evolve. Do patterns of gene expression change with similar temporal dynamics?
290 Some stem cells retain substrate stiffness ‘memory’ and commit to fate specific programs even
291 when transferred to a substrate with different stiffness [44,93]. Molecular mediators of such
292 mechanical ‘memory’ include microRNAs and YAP/TAZ pathway members [35,93,94]. One
293 example of this kind of ‘memory’ is provided by studies of mesenchymal stem cells (MSCs). When
294 cultured on stiff substrates, MSCs expressed higher levels of the microRNA *miR-21* than when
295 cultured on soft substrates. If these cells were first grown on stiff substrate, and then transferred

296 to a soft substrate, the expression profile associated with the stiff substrate persisted for days [94].
297 Knockdown of *miR-21* after initial growth on stiff substrate was sufficient to erase the
298 transcriptional profile associated with stiff substrates [94]. In another study of mechanical
299 ‘memory’ in MSCs using deformable hydrogels, initial culturing on stiff substrates increased YAP
300 levels in the nucleus, and this nuclear YAP persisted for ten days after substrate softening [93].

301 In addition to changing methylation patterns, nuclear heterochromatin undergoes
302 persistent force-specific changes. Exogenous forces acting on cells can decondense the
303 chromatin and increase protein diffusivity within the nucleoplasm [95]. Changes in chromatin and
304 protein mobility can persist tens of minutes after removal of exogenous forces [95].

305 Similar modulation of the physical properties of chromatin might facilitate the stabilizing
306 effects shown by Damodaran and colleagues [96]. They observed that compressive forces acting
307 on mouse fibroblasts cause nuclear import of HDAC3, which removes acetylation marks on
308 histones and thereby condenses the chromatin towards a quiescent state [96]. Additionally, they
309 observed that the initial geometry of the fibroblast cells was correlated with the transcriptional
310 response to the compressive force [96]. During embryonic development, similar cell types often
311 assume different geometries [97–99] as tissues undergo dramatic changes in form. For example,
312 different regions of a blastoderm epithelium will adopt different shapes at opposite poles of a
313 major body axis, or form tissue folds required for gastrulation. A promising avenue for further
314 research could be to determine whether specific geometries of groups of cells can also yield
315 disparate stable gene-expression outcomes because of physical pressures on chromatin (**Figure**
316 **3**), possibly resulting in progressive or terminal differentiation in response to large-scale tissue
317 movements.



318

319 **Figure 3. Coupling mechanical states with differential gene expression.** An epithelial tissue state (top
 320 row) and a corresponding hypothetical chromatin architecture (middle row) that gives rise to differential
 321 gene expression in particular cells (highlighted, bottom row). In tissues undergoing a mechanical transition
 322 from uniform stress/strain (**a**) to differential stress/strain (**b**) chromatin architecture may change according
 323 to the local forces experienced by the tissue. Under non-uniform stress, a range of chromatin architectures
 324 could emerge from varying local mechanical states (two such cases shown in **b**). Accessibility of specific
 325 genes to transcription factors could then vary across cells, resulting in differential gene expression. Nuclear
 326 shading is indicative of gene expression states: colored boxes correspond to the same three genic regions
 327 across states, and concentric dotted rings demarcate zones of chromatin accessibility (increasing from
 328 inside out).
 329

330 Just as the availability of transcription factor binding sites is carefully regulated, the
 331 response of chromatin architecture, and thus gene expression, to mechanical forces may also be
 332 carefully tuned. Sun and colleagues [100] showed that through changes in H3K9 methylation,
 333 cells can interpret both the frequency and magnitude of cyclic forces, translating these mechanical
 334 cues into varying levels of gene expression. Interestingly, they found that gene expression
 335 responses are not directly proportional to the magnitude or frequency of the applied forces, nor
 336 are they consistently linked to the extent of chromatin deformation. Instead, the absence of a clear
 337 correlation between these factors suggests a more nuanced regulatory mechanism that
 338 determines the optimal balance of mechanical cues driving specific transcriptional responses.

339 Collectively, these studies illuminate how mechanical forces can act as potent regulators
340 of gene expression, directing transcriptional outcomes through changes in chromatin
341 accessibility, nuclear architecture, and the strategic relocation of transcriptional machinery.
342 Extending this body of work to the developmental context will perhaps shed light on how large-
343 scale morphogenetic movements and evolving mechanical landscapes shape tissue- and stage-
344 specific gene expression programs. Deploying techniques including live non-toxic live staining,
345 specific pharmacological inhibition and force inference modelling, should allow future studies to
346 capture the emergent properties of multicellular systems—where dynamic, global changes in cell
347 shape and nuclear mechanics intersect with localized signaling events to drive robust
348 developmental outcomes. Understanding how these mechanical cues are sensed, transduced,
349 and ultimately manifested in stable or transient gene expression patterns will be critical for
350 determining the extent to which these fundamental processes are conserved or diverge across
351 evolutionary lineages, thus offering insights into the origins of the diversity of developmental
352 strategies observed in nature.

353

354 **2. Conserved morphogenetic materials across cells, tissues, and species**

355

356 Cells exist in myriad shapes that perform diverse functions individually as well as collectively. The
357 conserved mechanics of the cytoskeleton enable the emergence of tissue-level properties that
358 are fundamental to development and physiology. By bridging the gap between individual cell
359 behaviors and emergent tissue properties, the cytoskeleton ensures the complexity and
360 functionality of multicellular systems across diverse contexts. In this section, we focus particularly
361 on the physics of whole integrated cells and tissues as well as the cytoskeleton, which is
362 fundamental to crucial cell architectures and behaviors.

363 Understanding the physical dynamics of form requires imaging cells and tissues with high
364 temporal resolution. In the last several decades, much work looking at physical properties and
365 geometries of cells and tissues during embryogenesis has been limited to model species where
366 labels for live imaging of membranes, cytoskeleton, and adhesion molecules are readily available.
367 These model species span very few phyla, and achieving the goal of uncovering empirical laws
368 of collective cell behavior will thus require broadening the list of taxa studied. As more of these
369 tools are developed for a wider range of species, the emergent biophysical dynamics from studies
370 of model organisms can be contextualized within a comparative evolutionary
371 framework. Nevertheless, the great extent of conservation of cytoskeletal components and their
372 regulators across the cellular tree of life [101] allows us to generate hypotheses as to the general
373 biophysical mechanisms involved in regulating cytoskeletal dynamics during multicellular
374 morphogenesis and development.

375

376 2.1 Coordinating behaviour at the tissue level: regulation of actin dynamics via intercellular
377 adhesion

378 For coordinated movement at the tissue level, the internal cellular meshwork of a tissue
379 needs to be physically coupled. In animals, this is often achieved through intercellular adherens
380 junctions formed through cadherin family adhesion molecules [102] , including E-cadherin [103].
381 The intracellular domain of E-cadherin is mechanically coupled to cortical actin, leading to
382 emergence of mechanical continuity across tissues like epithelial sheets [103]. This mechanical
383 continuity is crucial for coordinated activity, force transmission across larger spatial scales, and
384 tissue integrity during several morphogenetic processes.

385 Biological processes can exhibit remarkable similarities in their underlying mechanisms,
386 even when they occur in vastly different contexts. For example, dorsal closure in *D. melanogaster*
387 embryos, neural tube closure in chordate embryos, and wound healing both embryonically and

388 postembryonically occur in very different biological contexts, yet they all deal with a gap closure,
389 making them topologically equivalent [104–107]. In all these cases, cadherin-mediated
390 mechanical coupling between the cells lining the gap enables the formation of a supracellular
391 actin cable [104,105,108]. Eventually, the gap is closed by the tightening of the actin cable in a
392 manner analogous to the drawing of purse strings [104,105]. These processes highlight how
393 conserved mechanical principles can drive diverse biological events.

394 While gap closure involves cells functioning together at a common spatial site, coordinated
395 cell behavior mediated by mechanical feedback can also guide cells to different locations to
396 perform their functions. In some well-studied collective migration phenomena, migrating cells
397 come to a halt or change direction upon collision, reminiscent of the trajectory of collision between
398 rigid bodies. This process is referred to as contact inhibition of locomotion (CIL) [109]. The tactile
399 feedback that cells receive through CIL is crucial, for example, for proper migration of neural crest
400 cells in *X. laevis* embryos, embryonic hemocytes in *D. melanogaster*, and during adult mammalian
401 wound healing, among other processes [110–112].

402 Much like repelling magnetic beads in a confined area assume a spatially uniform
403 distribution, CIL enables hemocyte (primary immune cells) dispersal, potentially enabling them to
404 survey the body effectively [111]. On collision, the intercellular adhesion molecules in the region
405 of contact in the colliding cells drive synchronous reorganization of the actin, resulting in the
406 formation of transient stress fibers that guide cellular repulsion [111]. The kinematics of cellular
407 repulsion mediated through CIL, acting at the timescale of a few minutes, resembles that of
408 colliding ice pucks occurring at a millisecond timescale.

409 While migrating cells avoid each other during CIL, in different developmental contexts cells
410 also exhibit coordinated movement, showcasing another layer of cellular cooperation [113].
411 During collective migration, establishing cellular polarity (i.e. a leading edge and a trailing edge of
412 the migrating cluster) is critical for directed migration, and this is achieved through asymmetric
413 localization of actomyosin and its regulators at the two ends of the group of migrating cells [114].

414 In the case of collective migration, the cluster of cells must establish polarity much like a single
415 migrating cell, but at a larger spatial scale [115]. The implication of this in several cases is the
416 emergence of distinct leader and follower cell phenotypes [115,116]. Border cell migration in the
417 *D. melanogaster* egg chamber provides a convenient system to investigate inter-cellular
418 cytoskeletal coordination, as the migrating cluster in this case consists of fewer than ten cells
419 [117]. Only the leader cell forms prominent protrusions, while moesin, a protein that links cortical
420 actin and the plasma membrane, helps curb protrusive activity in the follower cells [118,119].
421 Disruption of moesin activity in the follower cells frees cortical actin to form protrusions, adversely
422 affecting the collective motility of the cell cluster [119]. E-cadherin binding between the migrating
423 cluster and the underlying nurse cells (which act as a substrate for migration of the border cell
424 cluster) promotes forward-directed protrusions in the leader cell. The directionality is transmitted
425 to the follower cells through E-cadherin-mediated mechanical coupling between the border cells
426 [118]. This provides an illustration of how adherens junctions mechanically coupled to the
427 intracellular cytoskeleton enable a migrating cell cluster to behave as one large migrating cell
428 [118,119].

429 Different instances of collective cell migration can display unique, process-specific
430 features, including variation in the number of cells involved in the collective migration. For
431 example, *D. melanogaster* border cell migration involves approximately ten cells, wherein the
432 motile border cells collectively carry a pair of immotile polar cells [117]. In contrast, during
433 zebrafish and insect epiboly, thousands of cells move to cover the yolk in the absence of distinct
434 leader cells [52,120]. In other cases, collectives of very different sizes can nonetheless share
435 motile principles, including the presence of leader and follower cells. Zebrafish lateral line
436 primordium migration, for instance, involves distinct leader and follower cell fate, where the
437 leader cells have higher expression levels of receptors that can bind to the chemotactic cue,
438 than other cells in the collective. The remaining cells then follow the leader cells through
439 mechanical coupling between the two types of cells [121]. *D. melanogaster* embryonic tracheal

440 branching involves many fewer cells in the collective but is nonetheless also achieved by
441 migration involving distinct leader and follower cells. The tip cells (leaders), named for their
442 location in the tracheal branch, can sprout new branches, while stalk cells (followers) follow the
443 tip cell and complete the formation of tracheal tubes through proliferation and intercalation
444 [122].

445

446 2.2 Sensing mechanical stress at the cellular level: mechanosensitive ion channels

447 One of the ways that cells sense external mechanical stress is by deploying the Piezo
448 family of mechanosensitive ion channels [123]. First identified in mice as a pair of paralogous
449 genes (Piezo1 and Piezo2), Piezo homologs have since been characterized in *D. melanogaster*,
450 *Caenorhabditis elegans*, chickens, and other species [124–126].

451 Piezo 1 is critical for vasculature formation during angiogenesis in mice, zebrafish and
452 humans [127–130]. The Piezo1 ion channel responds to shear stress caused by blood flow by
453 opening and allowing an influx of Ca^{2+} ions, which act as a key signal for endothelial cell alignment
454 and migration [128]. Cell lines deficient in Piezo1 activity exhibit weak stress-induced Ca^{2+} entry,
455 and mice lacking Piezo1 are embryonic lethal, with most dying between embryonic days 9.5 and
456 11.5, a critical window for vascular development [128]. Furthermore, the activity of Piezo1 is tied
457 to actin dynamics, such that actin configuration at the membrane can determine the sensitivity of
458 Piezo1 [128].

459 Piezo2 is expressed in sensory neurons [124], and has well-studied neuronal roles in
460 mechanosensation [see for example 131–133]. Piezo2 can also play roles in sensing mechanical
461 stimuli in non-neuronal cells. In the urinary bladder, for example, they are expressed in non-
462 neuronal urothelial cells and are involved in sensing the stretch of the bladder [131]. Piezo2 aids
463 in touch sensation in a specialized non-neuronal skin cell type called Merkel cells [133–136], and
464 in chondrocytes, Piezo2 is involved in sending the mechanical strain experienced by joint cartilage

465 [137] . Suggestions that evolution of mechanosensory capabilities could involve evolutionary
466 changes in Piezo2 expression arise from work by Schneider and colleagues, who revealed that
467 ducks possess more Piezo2-expressing mechanoreceptors in their trigeminal ganglia, which
468 innervate the bill, tongue, and mouth cavity, than chickens [138]. Because ducks are thought to
469 rely more heavily on tactile stimulation for feeding than chickens, expression levels of Piezo2
470 could potentially be a component of the underlying mechanistic basis for evolutionary change in
471 tactile sensitivity between these birds. Electrophysiological recordings demonstrated a strong
472 correlation between Piezo2 expression and the presence of mechanosensitive neurons with
473 intermediate and slow mechanically activated (MA) currents [138], which could enhance tactile
474 awareness. Comparative analyses across six duck species revealed a strong correlation between
475 the fraction of Piezo2-expressing neurons in the trigeminal ganglia and the species' use of tactile
476 feedback for foraging [139]. This expansion of Piezo2-expressing neurons was coincident with a
477 reduction in the number of nociceptive neurons, suggesting a potential trade-off that enhances
478 tactile abilities in species less dependent on visual or olfactory cues [138,139]. Piezo2 regulates
479 the activity of RhoA, a regulator of actin cytoskeleton [140]. Membrane tension influences the
480 activation of Piezo channels, while membrane curvature is inversely correlated with the number
481 of Piezo channels embedded in the membrane [141,142]. Since cortical actin plays a key role in
482 regulating both membrane tension and curvature, it may work in conjunction with Piezo channels
483 to facilitate mechanosensation.

484

485 2.3 Viscoelasticity – a thermodynamic view of the cytoskeleton

486 On mixing oil and water, the immiscible droplets separate to form homotypic aggregates.
487 This aggregation minimizes surface tension as the surface area of the aggregate is lower than
488 the sum of individual droplet areas [143]. The interfacial tension that exists at the boundary
489 between oil and water is also minimized by homotypic aggregation. Heterotypic cell populations

490 also often segregate into homotypic spatial clusters, a process referred to as cell sorting [144–
491 146]. The striking similarity between cell sorting and surface tension-driven homotypic
492 aggregation has led many researchers to explore the cellular basis for surface tension. In 1963,
493 Malcolm Steinberg [147] proposed that differential adhesion between cell types was the major
494 driver of cell sorting, while Albert Harris [148] argued in 1976 that it was differential cell contractility
495 that drove the sorting. Subsequent experiments demonstrated that intercellular adhesion
496 molecules like cadherins are mechanically coupled to the intracellular actomyosin cytoskeleton
497 [149–151]. This coupling means that changes in actomyosin contractility can directly influence
498 cell adhesion strength and vice versa [149]. Since contractility generates tension at adhesion
499 sites, it affects how cells adhere and sort within tissues, integrating both Steinberg’s and Harris’s
500 theories.

501 Just as intercellular adhesion and contractility influence cell sorting through surface
502 tension-like mechanisms, they also contribute to the mechanical properties of individual cells,
503 determining their response to external forces. An elastic object under shear stress deforms and
504 regains its initial shape on removal of the applied stress, while liquids flow when shear stress is
505 applied [143]. Empirical studies, including those described in the following section, have shown
506 that cells behave like elastic solids on short timescales, resisting deformation under shear stress,
507 while flowing like viscous liquids at longer timescales. The contribution of the cytoskeleton to the
508 viscoelastic properties of the cell has been studied by measuring changes in viscoelasticity as
509 result of cytoskeletal perturbations [152,153]. Experiments on early-stage *D. melanogaster*
510 embryos have provided further insights into cytoskeleton-driven viscoelastic properties of
511 biological cells. In one such study, analyzing the trajectories of micrometer-sized injected
512 fluorescent beads revealed that the early syncytial embryo exhibited predominantly viscous
513 behavior with microtubules contributing to the viscous modulus [154]. To compare these
514 viscoelastic properties with those of the later stage blastoderm embryo, magnetic beads were
515 injected and then pulled by an external field [155]. This experiment revealed that while the

516 cytoplasm at this stage is largely viscous, as at the earlier stage of development, the cortex is
517 elastic in its response to applied external force. The later stage cortex exhibited an elastic
518 response over a timescale of four minutes, while deformations lasting longer than four minutes
519 yielded a viscous response. The viscosity of the cytoplasm turned out to be 1000-fold higher than
520 that of water [155]. These experiments on early *D. melanogaster* embryos provide insight into the
521 connection between cytoskeletal components and time-dependent viscoelastic cellular responses
522 to external forces.

523 Precise measurements of viscoelastic properties like those observed in the fly embryos
524 discussed above, are limited by scalability. To study morphogenetic processes at larger spatial
525 scales involving thousands of cells, alternative methods are needed to extract the mechanical
526 forces driving collective cell movement over time. In studies of epithelial sheet dynamics in the
527 gastrulating *D. melanogaster* embryo, physics-inspired models of epithelial sheets enabled
528 researchers to estimate membrane tension and internal cell pressures entirely from geometrical
529 properties like membrane curvature [156–158]. These estimates can in turn lead to inference of
530 forces driving tissue scale morphogenetic movements during development [77,156–158].
531 Descriptions of tissue level phenomena purely in terms of the viscoelastic properties of the
532 component cells is an approach that is applicable to larger spatial scales.

533 Thermodynamic descriptions of gases originated well before we knew about their microscopic
534 constitution [159]. Yet, it was not necessary to understand the atomic nature of gases to establish
535 quantitative empirical laws relating macroscopic properties like volume, pressure and
536 temperature, which were sufficient to build the steam engine that powered much of the industrial
537 revolution [159,160]. Statistical mechanics, the branch of physics that describes physical systems
538 in terms of their constituents, has shown how thermodynamic laws emerge from microscopic
539 interactions in the Avogadro limit [159]. Similar in spirit, the study of morphological processes
540 calls for both microscopic and macroscopic views of the system, depending on the spatial scale

541 of the phenomenon and the nature of the “mechanistic” explanation sought. At larger spatial
542 scales, purely microscopic descriptions like quantifying molecular gene products may prove
543 insufficient to explain morphogenesis. As the physicist P.W. Anderson famously stated, 'More is
544 different' [161], meaning that emergent phenomena are far more than the sum of their parts, and
545 a reductionist approach offers only limited insight. We posit that for the study of morphogenesis,
546 there is no single, absolute definition of the units or scale of explanatory mechanism that
547 constitutes “the real mechanism.” Rather, much like very detailed biomechanical analysis of bird
548 flight has limited utility for understanding flocking, the spatial scale of the phenomenon under
549 study must dictate the level of detail needed in describing the agents in a collective phenomenon
550 [162,163].

551

552 **3. Future Directions**

553

554 In conclusion, we address two broad classes of limitations inherent in current approaches and
555 suggest possible avenues forward through these challenges. We believe that finding ways to
556 overcome these challenges could lead to a deeper understanding not only of cellular mechanics,
557 but of the role of these parameters in morphological evolution.

558

559 3.1 Developing systematic approaches to finding mechanical drivers of morphogenesis

560 The mechanical mechanisms regulating morphogenesis that we have discussed here,
561 were primarily elucidated using what a geneticist would call a “candidate approach.” This
562 approach is essentially one of taking an educated guess as to the nature of a particular
563 mechanism based on prior knowledge of the mechanism operating in other contexts, and it has
564 been highly successful in the traditional fields of molecular genetics, developmental genetics, and

565 especially evolutionary developmental biology. In some of our examples [e.g. 45,48,54], particular
 566 physical or mechanical properties were observed or quantified, noted to correlate with specific
 567 morphogenetic processes, and hypothesized to be causally related to those processes.
 568 Subsequent experiments were aimed at perturbing the physical or mechanical parameters and
 569 assessing the impact on the morphogenetic process. In other examples [e.g. 3,44,50],
 570 researchers generated hypotheses about relevant mechanical or physical forces based on the
 571 perceived similarity of morphogenetic processes to physical behaviors characterized in other
 572 contexts.

573 While the “candidate gene” approach is useful in contexts where there is little a priori
 574 knowledge of genetic regulatory mechanisms, geneticists also seek and prize so-called “unbiased
 575 approaches” that uncover relevant genes by assessing the impacts of systematically perturbing
 576 many genes, either at random or chosen based on a broad unifying characteristic (e.g.
 577 transcription factors). Is there a way to discover mechanical mechanisms of morphogenesis using
 578 an unbiased approach? This is more challenging than performing a genetic screen, because there
 579 is no one-to-one mapping of mechanical parameters to genes or even specific biomolecules.
 580 Further, the “variables” of morphogenesis are ontologically distinct from, and not as cleanly
 581 defined as, those of a genetic screen (Table 1).

582

	Traditional genetic screen	Systematic mechanical analysis
Variables are	genes	emergent cell / tissue phenomena
	abstract entities (not directly observable)	observable descriptions of dynamic form
	cleanly transferable	emerge from locally specific environments
Perturbations	can be unbiased	cannot be completely unbiased (need to be situated in specific context)

583
 584 **Table 1.** The disparate nature of “variables” and “perturbations” in the context of traditional genetic screens,
 585 and our proposed approach of systematic mechanical analysis.
 586

587 However, one approach to understanding the nature of this mapping could be to perform a
588 forward genetic screen and assess the impacts on mechanical parameters already known to be
589 regulators of morphogenetic processes of interest. Data from such studies may also allow us to
590 understand the genetic basis of the evolution of mechanical properties. Whether the emergence
591 of significantly different mechanical properties between species is highly polygenic, or may be
592 explained through evolutionary changes in relatively few loci, remains an open question. A
593 systematic mechanical analysis conceptually analogous to a targeted genetic screen could
594 consist of developing morphogenetic assays for involvement of the classically recognized
595 Newtonian physical forces (for example, quantifying forces experienced or exerted by cells), and
596 systematically testing for their correlation with or involvement in a developmental process of
597 interest. This has proven fruitful in studies of morphogenesis in highly disparate contexts,
598 including fly wings, tunicate embryos, and plant leaves [164–167]. Applying this approach across
599 taxa is essential to understand not just the individual mechanical mechanisms of each case study,
600 but more importantly, the range of processes that they can regulate, and their interdependencies
601 during development.

602 A third approach could attempt to screen for mechanical mechanisms based on morphological
603 output. Such an approach could test the hypothesis that, for example, similar morphologies are
604 achieved through a conserved set of physical mechanisms. There may be an opportunity here for
605 machine learning approaches to construct a collection of topologically similar cell or tissue
606 morphologies (e.g. the branches of plant roots or neural dendrites, or the tubes of renal or
607 bronchial systems) using image data that could span broad phylogenetic ranges, potentially
608 pointing towards common underlying mechanical principles across broad domains of life.

609 We suggest that by pursuing one or more of these approaches going forward, the field may
610 be able to shift our understanding from the level of individual case studies to determining the
611 extent of pattern and predictability in the mechanical control of morphogenesis. However, the
612 bottleneck to this approach will likely be, as is the case for traditional forward genetic screens, the

613 efficiency and throughput of phenotyping. The phenotypes often quantified in mechanical studies
614 of development – for example, tissue flows assessed or material properties of cells – are usually
615 obtained with low-throughput approaches like high-resolution live imaging or atomic force
616 microscopy. New and creative methods for obtaining mechanical and material phenotypes at
617 scale will need to be developed. Recent attempts to infer cellular forces from light microscopy
618 data [e.g. 77,157,158] are an example of one promising approach to overcoming this challenge.

619

620 3.2 Detecting natural variation in the mechanics of morphogenesis between and within species

621 Much of our understanding of the mechanisms discussed here has been obtained from
622 exogenous mechanical or material perturbations of morphogenesis. However, as briefly
623 mentioned in section 1.1 above, how the scale of these perturbations relates to the endogenous
624 scales of tissue forces and properties is unknown. Obtaining at least biologically relevant
625 boundary conditions, if not precise system-specific measurements, for these properties will be
626 important if we wish to understand whether and how they may contribute to the evolutionary
627 process.

628 We suggest three potential roads forward. The first is to, as suggested in 3.1 above, develop
629 new methods to measure relevant properties in live, intact tissue systems, or creative inference
630 of these properties from existing static or dynamic data. The second is to compare these
631 properties and mechanisms between taxa across a range of phylogenetic distances. Such
632 comparisons may allow us to understand what determines the degree of conservation of
633 mechanical mechanisms, and to what extent they may be predicted based on evolutionary
634 relationships, as can sometimes be done for molecular functions [168]. Third, to determine the
635 extent of standing variation and thus potential evolvability of these mechanisms, genotyped
636 collections of populations of a single species [169,e.g. 170–173] could be screened to quantify

637 the variance of the key parameters governing the mechanical mechanisms that regulate
638 morphogenesis.

639

640 **Statement on AI/LLM use**

641 No content was generated using artificial intelligence. ChatGPT 4.0 (OpenAI) was used to check
642 for grammatical errors, improve language flow and readability of parts of the text. Scite_(scite.ai)
643 was used for mining references and topic-based literature searches. All AI-suggested references
644 and content were manually checked for accuracy.

645

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652

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